

STAT 593

Smoothing

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Outline

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Inf convolution / epigraph addition

Definition

The **inf-convolution** of two functions $f_1, f_2 : \mathbb{R}^d \mapsto \mathbb{R}$ is denoted $f_1 \square f_2$, where

$$(f_1 \square f_2)(x) = \inf_{(u_1, u_2) \in \mathbb{R}^d \times \mathbb{R}^d} \{f_1(u_1) + f_2(u_2) : u_1 + u_2 = x\}$$

$$(f_1 \square f_2)(x) = \inf_{u \in \mathbb{R}^d} \{f_1(u) + f_2(x - u)\}$$

- ▶ $f_1 \square f_2 = f_2 \square f_1$
- ▶ For closed convex f_1 and f_2 , provided they share a common affine minorant, then $f_1 \square f_2$ is a convex closed function s.t.

$$\text{epi}(f_1 \square f_2) = \text{epi}(f_1) + \text{epi}(f_2)$$

Properties

Notation: $d_{\mathcal{C}}(x) = \inf_{c \in \mathcal{C}} \|x - c\|$, $\iota_{\mathcal{C}}(x) = \begin{cases} 0 & \text{if } x \in \mathcal{C} \\ +\infty & \text{if } x \notin \mathcal{C} \end{cases}$

f_1	f_2	$f_1 \square f_2$
f	0	$\inf_{x \in \mathbb{R}^d} f(x)$
$\iota_{\mathcal{C}}$	$\ \cdot\ $	$d_{\mathcal{C}}$
$\iota_{\mathcal{C}}$	$\iota_{\mathcal{D}}$	$\iota_{\mathcal{C}+\mathcal{D}}$
f	$\iota_{\{x\}}$	$f(\cdot - x)$
f	$\langle s, \cdot \rangle$	$\langle s, \cdot \rangle - f^*(s)$
f	f	$2f(\frac{\cdot}{2})$ (f convex)

Fenchel and inf-convolution¹

Theorem

For any function f and g , one has

$$(f \square g)^* = f^* + g^*$$

Proof: simply write the definition

¹H. H. Bauschke and P. L. Combettes. *Convex analysis and monotone operator theory in Hilbert spaces*. New York: Springer, 2011, pp. xvi+468.

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Inf convolution

Moreau envelope

Moreau envelope²

Definition

The Moreau envelope of the function f of parameter $\gamma > 0$ is

$$\gamma f := f \square \left(\frac{1}{2\gamma} \|\cdot\|^2 \right)$$

i.e.,

$$\gamma f(x) := \inf_{u \in \mathbb{R}^d} \left\{ f(u) + \frac{1}{2\gamma} \|x - u\|^2 \right\}$$

Rem: when f is closed and convex the inf is a min

Rem: γ has the role of a smoothing parameter

²J.-J. Moreau. "Fonctions convexes duales et points proximaux dans un espace hilbertien". In: *C. R. Acad. Sci. Paris* 255 (1962), pp. 2897–2899.

Pinball case

For $s_1 \leq 0 \leq s_2$ let us define the general pinball loss :

$$\ell_{s_1, s_2}(x) = \begin{cases} s_1 x & \text{if } x \leq 0 \\ s_2 x & \text{if } x \geq 0 \end{cases}$$

Then, writing $f = \ell_{s_1, s_2}$ and $g = \frac{|\cdot|^2}{2\gamma}$, the Moreau envelope ${}^\gamma f$ is defined for any $x \in \mathbb{R}$ by

$${}^\gamma f(x) = (f \square g)(x) = \begin{cases} s_1 x - \gamma \frac{s_1^2}{2}, & \text{if } x < s_1 \\ \frac{1}{2\gamma} x^2, & \text{if } x \in [\gamma s_1, \gamma s_2] \\ s_2 x - \gamma \frac{s_2^2}{2}, & \text{if } x > s_2 \end{cases}$$

Rem: a classical example is the Huber function, when one considers the absolute value function $|\cdot| = \ell_{-1,1}$:

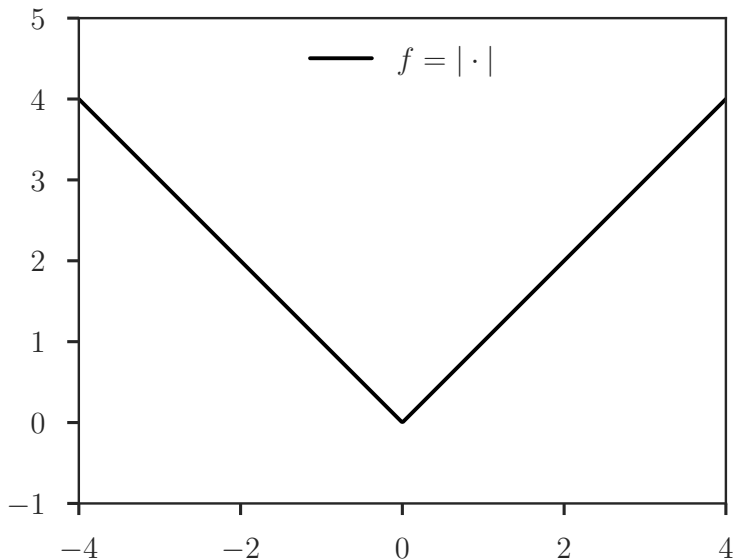
Intermission

Movie!

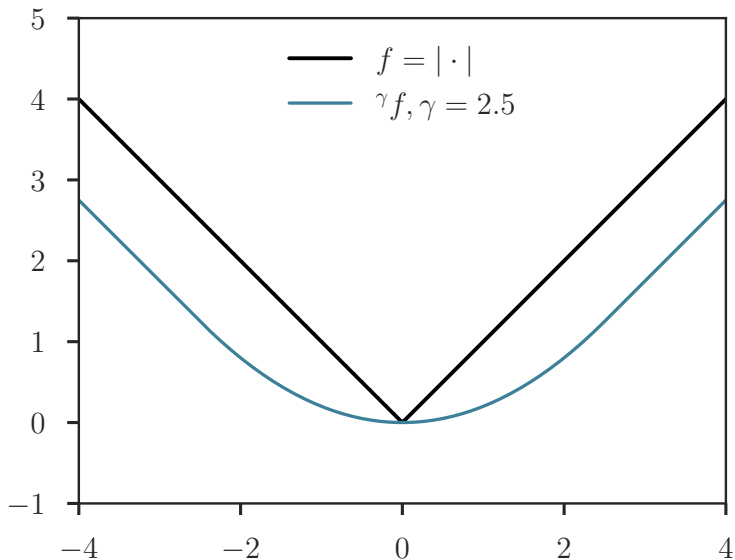
Proof

- ▶ if $u < 0$: the Fermat rule leads to $u = x - \gamma s_1$ (and $x < \gamma s_1$)
so $(f \square g)(x) = s_1(x - \gamma s_1) + \gamma \frac{s_1^2}{2} = s_1 x - \gamma \frac{s_1^2}{2}$
- ▶ if $u > 0$: the Fermat rule leads to $u = x - \gamma s_2$ (and $x > \gamma s_2$)
 $(f \square g)(x) = s_2(x - \gamma s_2) + \frac{\gamma s_2^2}{2} = s_2 x - \gamma \frac{s_2^2}{2}$
- ▶ if $u = 0$: the Fermat rule and noticing that $\partial \ell_{s_1, s_2}(0) = [s_1, s_2]$ leads to $\frac{x-u}{\gamma} = \frac{x}{\gamma} \in [s_1, s_2]$.

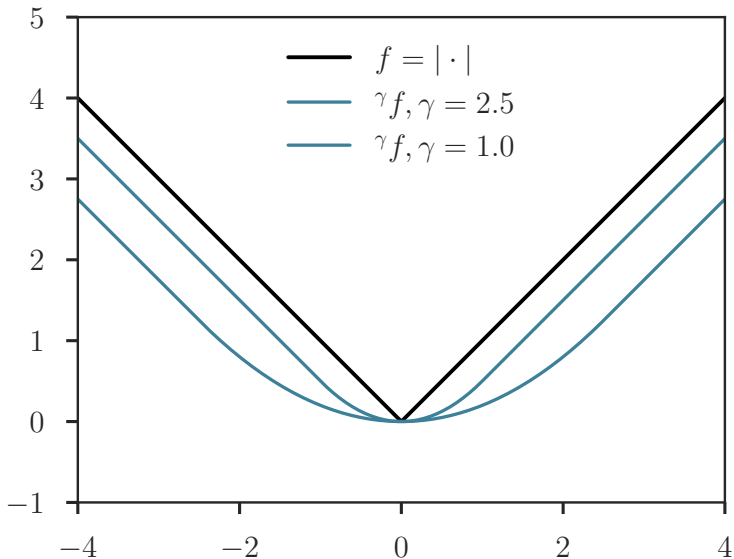
Influence of the smoothing parameter γ



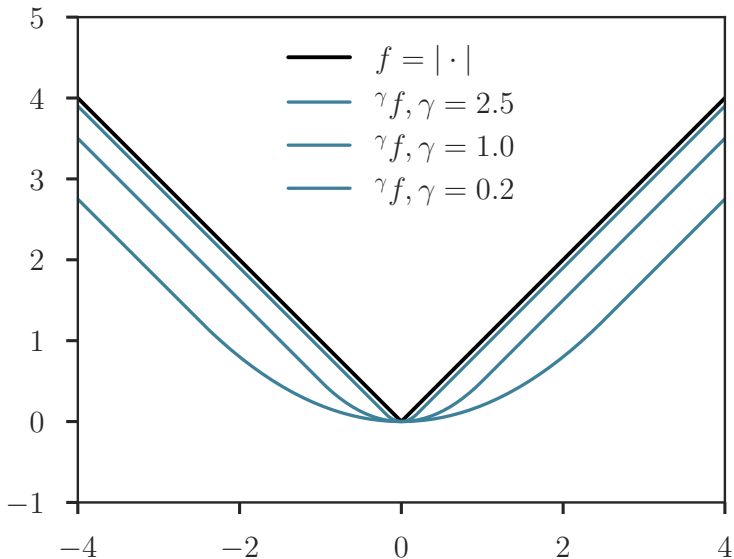
Influence of the smoothing parameter γ



Influence of the smoothing parameter γ



Influence of the smoothing parameter γ



Sharing inf/minimum

Theorem

A function f and its Moreau envelopes share the same minima:

$$\forall \gamma > 0, \quad \inf_x ((\gamma f)(x)) = \inf_x f(x)$$

Proof:

$$\begin{aligned} \inf_x ((\gamma f)(x)) &= \inf_x \inf_y \left\{ f(y) + \frac{1}{2\gamma} \|x - y\|^2 \right\} \\ &= \inf_y \inf_x \left\{ f(y) + \frac{1}{2\gamma} \|x - y\|^2 \right\} \\ &= \inf_y f(y) \end{aligned}$$



Proximal / Moreau

Recall for the convex case:

$$\begin{aligned} \gamma f(x) &:= \min_{u \in \mathbb{R}^d} \left\{ f(u) + \frac{1}{2\gamma} \|x - u\|^2 \right\} \\ \text{prox}_{\gamma f}(x) &:= \arg \min_{u \in \mathbb{R}^d} \left\{ f(u) + \frac{1}{2\gamma} \|x - u\|^2 \right\} \end{aligned}$$

Moreau decomposition: $\text{Id} = \text{prox}_f + \text{prox}_{f^*}$

Link proximal operators / Moreau envelopes

Note that by rearranging terms

$$\begin{aligned}\gamma f(x) &= \frac{1}{2\gamma} \|x\|^2 - \frac{1}{\gamma} \sup_y \left(\langle x, y \rangle - \gamma f(y) - \frac{1}{2} \|y\|^2 \right) \\ &= \frac{1}{2\gamma} \|x\|^2 - \frac{1}{\gamma} \left(\gamma f + \frac{1}{2} \|\cdot\|^2 \right)^* (x)\end{aligned}$$

Hint: remind that

$$s \in \arg \max_{t \in \mathbb{R}^d} \langle t, x \rangle - f^*(t) \iff s \in \partial f(x) \iff x \in \partial f^*(s)$$

$$\begin{aligned}\nabla \gamma f(x) &= \frac{x}{\gamma} - \frac{1}{\gamma} \arg \max_y \left(\langle x, y \rangle - \gamma f(y) - \frac{1}{2} \|y\|^2 \right) \\ &= \frac{1}{\gamma} (x - \text{prox}_{\gamma f}(x))\end{aligned}$$

Consequence: γf is $\frac{1}{\gamma}$ -Lipschitz !

Smoothing generalization

Nesterov (2005), Beck and Teboulle (2012)

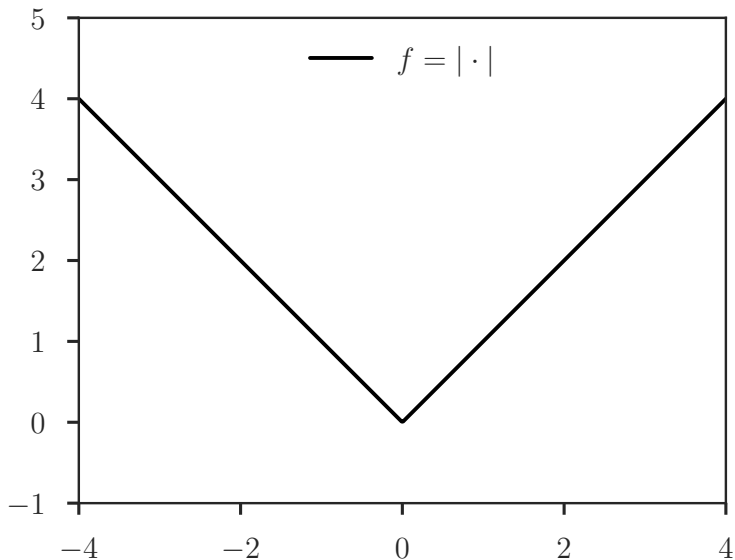
Motivation: smooth a non-smooth function f to ease optimization

Smoothing step: for $\gamma > 0$, a “smoothed” version of f is $\mathfrak{J}_\gamma f$

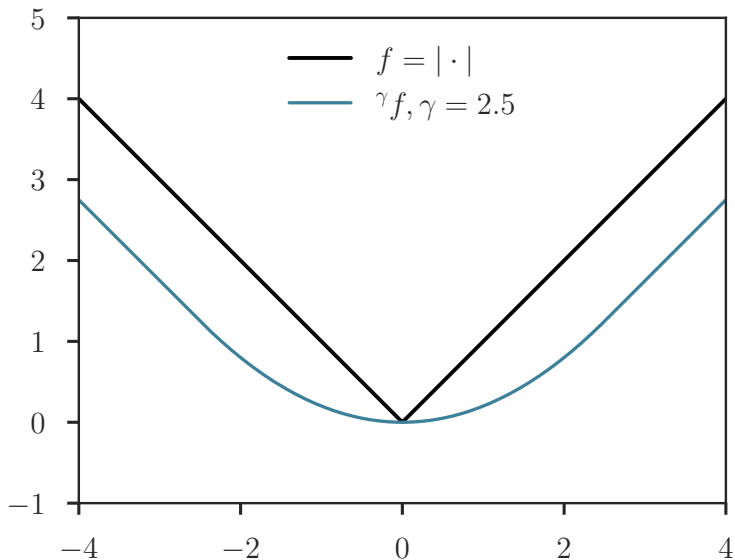
$$\begin{aligned}\mathfrak{J}_\gamma f &= \gamma \omega \left(\frac{\cdot}{\gamma} \right) \square f \\ &= (f^* + \gamma w^*)^*\end{aligned}$$

- ▶ $\omega = \frac{1}{2} \|\cdot\|^2$ recovers the Moreau envelop and we can drop the index ω
- ▶ ω is a predefined smooth function (s.t. $\nabla \omega$ is L_ω Lipschitz)

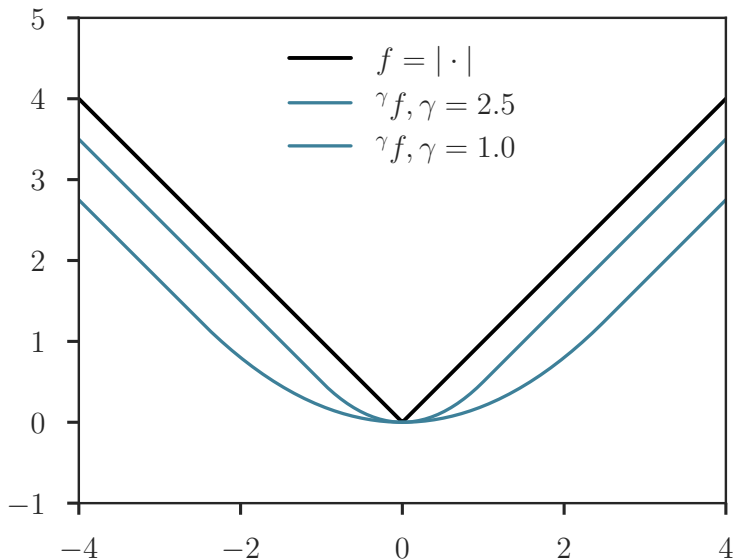
Huber function: $\omega(t) = \frac{t^2}{2}$



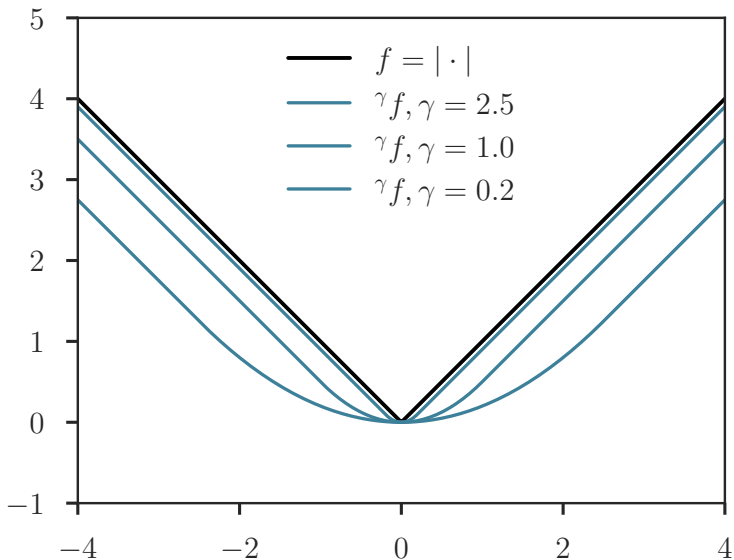
Huber function: $\omega(t) = \frac{t^2}{2}$



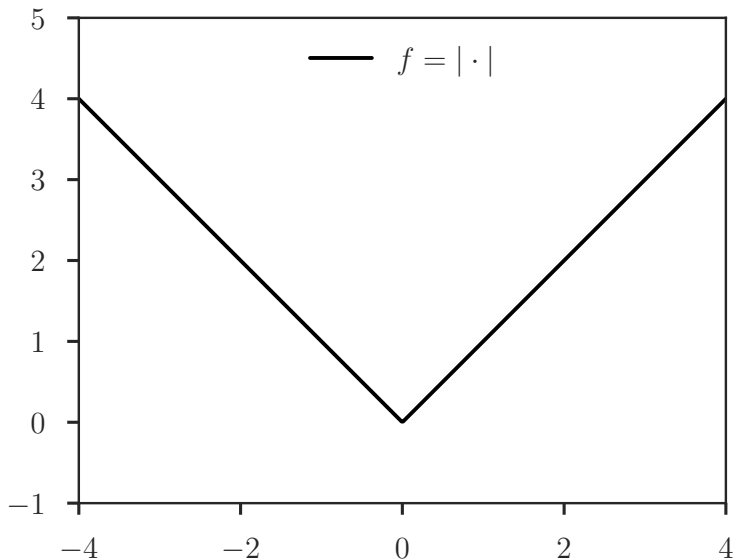
Huber function: $\omega(t) = \frac{t^2}{2}$



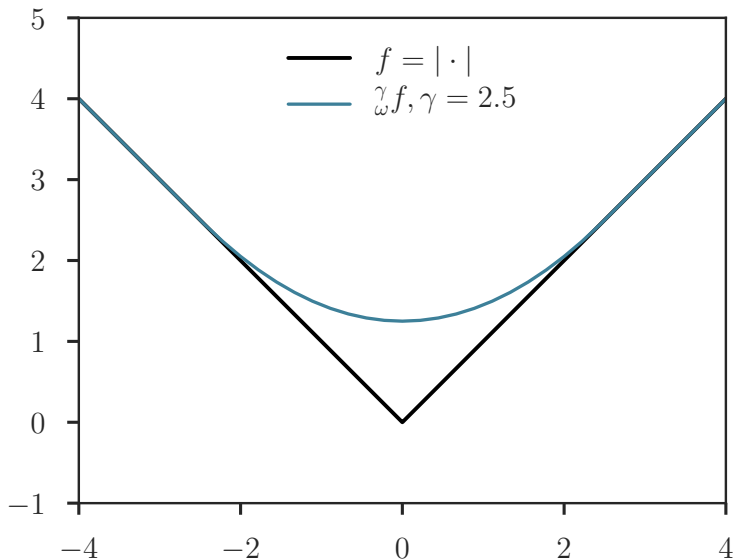
Huber function: $\omega(t) = \frac{t^2}{2}$



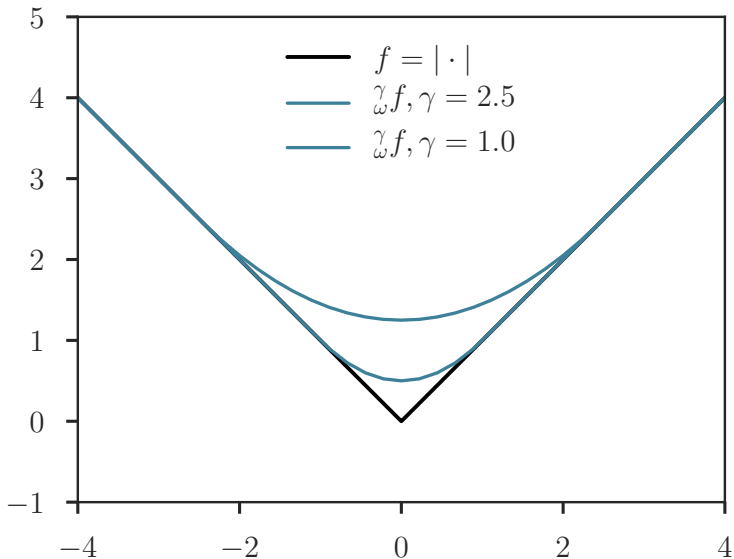
Huber function (bis): $\omega(t) = \frac{t^2}{2} + \frac{1}{2}$



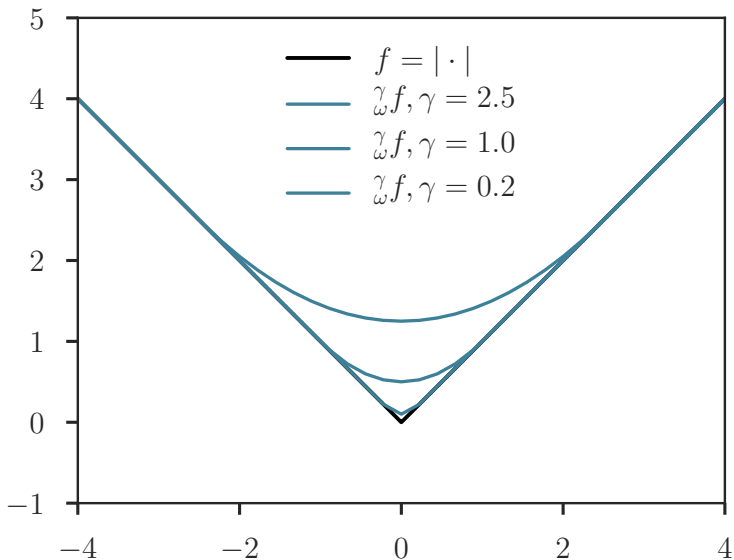
Huber function (bis): $\omega(t) = \frac{t^2}{2} + \frac{1}{2}$



Huber function (bis): $\omega(t) = \frac{t^2}{2} + \frac{1}{2}$



Huber function (bis): $\omega(t) = \frac{t^2}{2} + \frac{1}{2}$



Link: Fourier / Legendre transforms and kernel smoothing

Kernel
smoothing
analogy:

Fourier/Laplace : $\mathcal{F}(f)$	Fenchel/Legendre: f^*
convolution: \star	inf-convolution: \square
$\mathcal{F}(f \star g) = \mathcal{F}(f) \cdot \mathcal{F}(g)$	$(f \square g)^* = f^* + g^*$
Gaussian : $\mathcal{F}(g) = g$	$\omega = \frac{\ \cdot\ ^2}{2} : \omega^* = \omega$
$f_h = \frac{1}{h} g\left(\frac{\cdot}{h}\right) \star f$	$\gamma f = \gamma \omega\left(\frac{\cdot}{\gamma}\right) \square f$

Smoothing and approximation³

Theorem

Let f be a closed function with:

$$\omega f = \gamma \omega \left(\frac{\cdot}{\gamma} \right) \square f$$

Then, for any $\gamma > 0$ and $x \in \mathbb{R}^d$, one has

$$f(x) - \gamma \omega^*(g_x) \leq \omega f(x) \leq f(x) + \gamma \omega(0)$$

where $g_x \in \partial f(x)$.

³A. Beck and M. Teboulle. "Smoothing and first order methods: A unified framework". In: *SIAM J. Optim.* 22.2 (2012), pp. 557–580.

Proof

Fact 1: $\gamma f(x) = \inf_{y \in \mathbb{R}^d} \left\{ f(y) + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\} \leq f(x) + \gamma \omega(0)$

(1)

(2)

Proof

Fact 1: $\gamma f(x) = \inf_{y \in \mathbb{R}^d} \left\{ f(y) + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\} \leq f(x) + \gamma \omega(0)$

Fact 2:

(1)

(2)

Proof

Fact 1: $\gamma f(x) = \inf_{y \in \mathbb{R}^d} \left\{ f(y) + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\} \leq f(x) + \gamma \omega(0)$

Fact 2:

$$\gamma f(x) - f(x) = \inf_{y \in \mathbb{R}^d} \left\{ f(y) - f(x) + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\}$$

(1)

(2)

Proof

Fact 1: $\gamma f(x) = \inf_{y \in \mathbb{R}^d} \left\{ f(y) + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\} \leq f(x) + \gamma \omega(0)$

Fact 2:

$$\begin{aligned} \gamma f(x) - f(x) &= \inf_{y \in \mathbb{R}^d} \left\{ f(y) - f(x) + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\} \\ &\stackrel{(1)}{\geq} \inf_{y \in \mathbb{R}^d} \left\{ \langle g_x, y-x \rangle + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\} \end{aligned}$$

(1) sub-gradient definition at point x

(2)

Proof

Fact 1: $\gamma f(x) = \inf_{y \in \mathbb{R}^d} \left\{ f(y) + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\} \leq f(x) + \gamma \omega(0)$

Fact 2:

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(1) sub-gradient definition at point x

(2)

Proof

Fact 1: $\gamma f(x) = \inf_{y \in \mathbb{R}^d} \left\{ f(y) + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\} \leq f(x) + \gamma \omega(0)$

Fact 2:

$$\begin{aligned} \gamma f(x) - f(x) &= \inf_{y \in \mathbb{R}^d} \left\{ f(y) - f(x) + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\} \\ &\stackrel{(1)}{\geq} \inf_{y \in \mathbb{R}^d} \left\{ \langle g_x, y-x \rangle + \gamma \omega \left(\frac{x-y}{\gamma} \right) \right\} \\ &\geq \inf_{z \in \mathbb{R}^d} \gamma \{ \langle g_x, -z \rangle + \omega(z) \} \\ &\geq -\gamma \omega^*(g_x) \end{aligned}$$

(1) sub-gradient definition at point x

(2) $\inf(-f) = -\sup f$

Approximation

Theorem

Let us denote $\omega_\gamma := \gamma\omega \left(\frac{\cdot}{\gamma} \right)$, so

$$\omega_\gamma f = \gamma\omega \left(\frac{\cdot}{\gamma} \right) \square f = (f^* + \gamma w^*)^* = (f^* + w_\gamma^*)^*$$

Let ω have gradient L_ω -Lipschitz. Then, for any $\gamma > 0$ and $x \in \mathbb{R}^d$, $\omega_\gamma f$ has gradient $\frac{L_\omega}{\gamma}$ -Lipschitz

Proof:

Fact 1: $\omega_\gamma := \gamma\omega \left(\frac{\cdot}{\gamma} \right)$ has gradient $\frac{L_\omega}{\gamma}$ -Lipschitz

Fact 2: a function h has gradient L_h -Lipschitz iff its conjugate h^* is $\frac{1}{L_h}$ -strongly convex; see [Th. 4.2.1. Hiriart-Urruty and Lemarechal \(1993b\)](#)

Relying on the two previous facts, the result holds true.

More references

- ▶ Material mostly inspired by the lecture notes by Pontus Giselsson:
<http://www.control.lth.se/ls-convex-2015/>
- ▶ Remark on naming : inf-convolution see Hiriart-Urruty and Lemarechal (1993), Remark 2.1.4.
- ▶ <https://statweb.stanford.edu/~candes/math301/Lectures/Moreau-Yosida.pdf>
- ▶ full details and proof in Bauschke and Combettes (2011)

Examples for (geometric) median computation

Definition

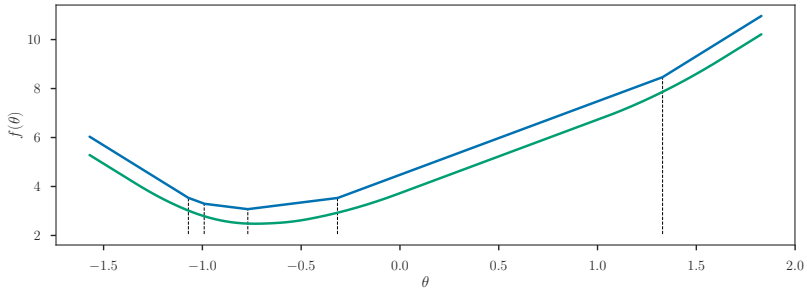
(Geometric) Median : $\text{Med}_n(\mathbf{x}) \in \arg \min_{\theta \in \mathbb{R}^d} \sum_{i=1}^n \|x - x_i\| = f(x)$

A possible approach to solve this problem is to perform smoothing with $\omega = \frac{1}{2} \|\cdot\|^2$ and γ , which leads to solve the Huber-mean :

$$\arg \min_{\theta \in \mathbb{R}^d} \sum_{i=1}^n H_{\gamma}(x - x_i)$$

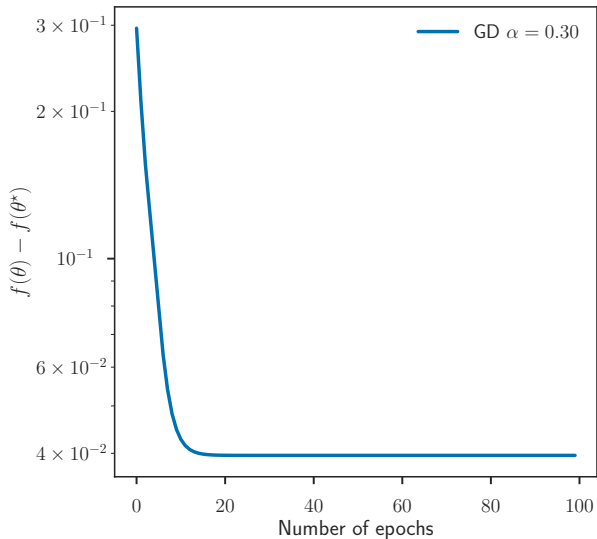
$$\text{where } H_{\gamma}(z) = \begin{cases} \frac{\|z\|^2}{2\gamma} & \|y\| \leq \gamma \\ \|y\| - \frac{\gamma}{2} & \|y\| > \gamma \end{cases}$$

Visualisation



TO DO: add legend: Green is the smooth approximation

Optimization



References I

- ▶ Bauschke, H. H. and P. L. Combettes. *Convex analysis and monotone operator theory in Hilbert spaces*. New York: Springer, 2011, pp. xvi+468.
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- ▶ Moreau, J.-J. “Fonctions convexes duales et points proximaux dans un espace hilbertien”. In: *C. R. Acad. Sci. Paris* 255 (1962), pp. 2897–2899.
- ▶ Nesterov, Y. “Smooth minimization of non-smooth functions”. In: *Math. Program.* 103.1 (2005), pp. 127–152.